

Amendments to the Specification:

Please amend paragraph 0049 of the specification as follows:

[0049] Nevertheless, it is possible to fix a threshold $[[th]]$ beyond which it is considered that the estimated orientation is sufficiently close to the orientation measured to be validated. This can take place by means of a second comparator 16 provided to compare the difference $\Delta\Theta$ with the threshold value $[[th]]$.

Please delete the following on Page 15 of the specification:

~~LITERATURE~~

~~[0078] (1) U.S. Pat. No. 5,953,683, "Sourceless orientation sensor" by Kogan Vladimir et al.~~

~~[0079] (2) U.S. Pat. No. 6,702,708, "A miniature, sourceless, networked, solid state orientation module" by Christopher Townsend et al., MicroStrain Inc. 294 N. Winooski Ave., Burlington, Vt. 05401, USA~~

~~[0080] (3) "A miniature, sourceless, networked, solid state orientation module", by Christopher Townsend, David Guzik, Steven Arms, MicroStrain Inc., 294 N. Winooski Ave., Burlington, Vt. 05401, USA, pages 44 to 50.~~

~~[0081] (4) "Methode de calcul numerique" [Numerical calculation method] by J. P. Nougier, 3rd edition 1987, Edition Masson, pages 54-58.~~